

Phys 1501 review 2

1) sliding blocks

Strategy

Look at 2 blocks separately (look at diagram on screen)

Top block has a contact force exerted by the bottom block

Normal force N_1 and frictional force $-.4N_1$ (using coefficient of friction)

Other forces are tension from string + weight (gravity)

Bottom block has $-N_1$ and $.4N_1$ with top block

N_2 and $.4N_2$ with floor

Other forces: $-P$ (applied force), tension, and weight

Solution

Constant speed = no acceleration

Newton's second law: $\sum F = ma \rightarrow \sum F_x = m_1 a_x$

$\sum F_y = m_1 a_y$

Top $T - .4N_1 = 0$

$N_1 - 19.6W = 0$

$N_1 = 19.6$

$T = 7.84N$

Bottom

$\sum F_x = m_1 a_x = 0$

$\sum F_y = m_1 a_y = 0$

$T - P + .4N_1 + .4N_2 = 0$

$N_2 - 39.2W - N_1 = 0$

$N_2 = 58.8W$

$P = 39.2N$

2) Power

Strategy

constant velocity (90 km/h) so net work = 0 $\rho F \cdot d$

Power (engine) = gravity + air resistance
 \uparrow 75% \uparrow 25%

$$m\vec{g} \cdot \vec{v} = mgv \sin \theta$$

$$15\% \text{ grade} \rightarrow \tan \theta = 0.15$$

Solution

$$P = m\vec{g} \cdot \vec{v} = mgv \sin \theta$$

$$0.75P = mgv \sin(\tan^{-1}(0.15))$$

$$P = \frac{(1200 \cdot 9.8) (90 \text{ m/3.6s}) \sin(1.53)}{0.75} = 58 \text{ kW (78 hp)}$$

Center of mass

strategy

Use center of earth as center of system

Solution

$$R = \frac{m_{\text{earth}} r_{\text{cm}} + m_{\text{iron}} r_{\text{cm}}}{m_{\text{earth}} + m_{\text{iron}}}$$

$$r_{\text{e}} = 0 \text{ m}$$

$$R = \frac{(5.97 \times 10^{24})(0) + (7.36 \times 10^{22})(3.87 \times 10^7)}{5.97 \times 10^{24} + 7.36 \times 10^{22}} = 4.64 \times 10^6$$

Radius of earth is 6.37×10^6 so -4.64×10^6 means a $1.73 \times 10^6 \text{ m}$ radius ^{1000 miles} for system below earth's surface

4) Conservation of momentum

a) We want conservation of momentum so we need a closed system

System: hammer + Iron man from collision to right before hitting tree

M_H = mass of hammer

M_I = mass of Iron man

v_H = velocity of hammer before hitting Iron man

v = combined velocity of Iron man + Hammer after collision

Iron man
 $v_0 = 0$

$$M_H v_H = (M_H + M_I) v \rightarrow M_H v_H = M_H v + M_I v \rightarrow M_H (v_H - v) = M_I v$$

$$M_H = \frac{M_I v}{v_H - v} = \frac{200 \text{ kg} \left(\frac{2 \text{ m}}{.75 \text{ s}} \right)}{10 \frac{\text{m}}{\text{s}} - \left(\frac{2 \text{ m}}{.75 \text{ s}} \right)} = 73 \text{ kg}$$

Momentum conserved

b) $KE_{\text{initial}} \rightarrow K_i = \frac{1}{2} M_H v_H^2$ ← all in the hammer

$$= \frac{1}{2} (70 \text{ kg}) (10 \text{ m/s})^2 = 3500 \text{ J}$$

$$K_f = \frac{1}{2} (M_H + M_I) v^2$$

$$= \frac{1}{2} (70 \text{ kg} + 200 \text{ kg}) (2.67 \text{ m/s})^2 = 966 \text{ J}$$

$$K_f - K_i = 3500 \text{ J} - 966 \text{ J} = 2534 \text{ J} \quad \text{Energy not conserved}$$

5) Inelastic collisions

strategy

Define the system to be 2 particles. Inelastic collision because they stick. Momentum conserved, KE is not

Solution

$$Mv_p - Mv_n = 2Mv_d \rightarrow v_p - v_n = 2v_d \quad 7E6 - 4E6 = 2v_d$$

$$\vec{v}_d = (1.5E6 \text{ m/s}) \begin{matrix} \uparrow \\ \leftarrow \end{matrix} \quad v_d = 1.5E6 \text{ m/s}$$

x direction

6) Rotational kinematics

strategy

a) $\bar{\omega} = \frac{\Delta\omega}{\Delta t}$ average angular velocity
average angular accel

$$\Delta\omega = \omega_f - \omega_i = 250 \text{ rev/min} \quad \Delta t = 5$$

b) know α and $\Delta\omega$ stopping time $\Delta t = \frac{\Delta\omega}{\alpha}$

Solution

$$a) \alpha = \frac{\Delta\omega}{\Delta t} = \frac{250 \text{ rev}}{5}$$

Need rad/s from rpm

$$\alpha = \frac{26.2 \text{ rad/s}}{5} = 5.24 \text{ rad/s}^2$$

$$\Delta\omega = 250 \frac{\text{rev}}{\text{min}} \cdot \frac{2\pi \text{ rad}}{\text{rev}} \cdot \frac{1 \text{ min}}{60 \text{ sec}} = 26.2 \text{ rad/sec}$$

b) ω goes from 26.2 rad/s to 0 $\rightarrow \Delta\omega = -26.2 \text{ rad/s}$

$$\Delta t = \frac{-26.2 \text{ rad/s}}{-5.24 \text{ rad/s}^2} = 0.3 \text{ sec}$$

7) Moment of inertia

Strategy / Solution

a) Definition of inertia for a system and sum

$$I = \sum_j m_j r_j^2 = (0.02\text{kg}) (2(0.25\text{m})^2 + 2(0.15\text{m})^2 + 2(0.05\text{m})^2) = 0.0035 \text{ kg m}^2$$

b) $I = \sum_j m_j r_j^2 = (0.02\text{kg}) (2(0.25)^2 + 2(0.15)^2) = 0.0034 \text{ kg m}^2$ \rightarrow Very similar

c) Rotational kinetic energy (K) = $\frac{1}{2} I \omega^2$

$$K = \frac{1}{2} I \omega^2 = \frac{1}{2} (0.0035 \text{ kg m}^2) (5 \cdot 2\pi \text{ rad/s})^2 = 1.73 \text{ J}$$

8) Torque

Strategy

Find each torque individually (using cross product) + determine sign.
Then add

Solution

\vec{F}_1 is opposite so $150 - 20 = 130^\circ$

RHR is out of page (positive)

$$|\vec{\tau}_1| = r F_1 \sin 130 = 0.5 \text{ m} (20 \text{ N}) (0.5) = 5 \text{ Nm}$$

\vec{F}_2 is at 90°

RHR is into page (negative)

$$|\vec{\tau}_2| = -r F_2 \sin 90 = -0.5 \text{ m} (30 \text{ N}) = -15 \text{ Nm}$$

\vec{F}_3 is at $0^\circ \rightarrow$ No torque ($\sin 0 = 0$)

$$\tau_{\text{net}} = \sum_i |\vec{\tau}_i| = 5 - 15 = -10 \text{ Nm}$$